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When is it safe to free memory in concurrent programming?

An opinionated survey of memory reclamation algorithms

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Concurrent Data Structures (CDS)



- + fast & non-blocking
- complex design

- T. . . .

- memory management

Memory Reclamation in CDS: You Are Not Free to free() the Removed Block



Solution: Safe Memory Reclamation (SMR) Algorithms

The SMR Algorithms Literature



SMR Algorithm #1 Hazard Pointers (HP)



Q2: When is it safe to free(b)?

A2: When it is no longer protect()'ed.

HP's Example HP-Protected Treiber's Stack

```
struct Node<T> { Node<T>* next; T data: }:
                   1
                       struct Stack<T> {
                   2
                        Atomic<Node<T>*> head;
                                                 // nullptr, initially
                   3
                        void push(T data) {
                   4
                           auto node = new Node<T>{nullptr, data};
                   5
                          do {
                   6
                            auto cur = this->head.load();
                   7
                            node->next = cur;
                   8
                          } while (!this->head.cas(cur, node));
                   9
                  10
                                                                    protect(cur);
                         optional<T> Stack<T>::pop() {
                  11
                           auto cur = nullptr;
                                                                    if (this->head.load() != cur)
                  12
                          loop {
                  13
                                                                         continue;
                            cur = this->head.load();
                  14
                             if (cur == nullptr) return {};
                  15
unsafe
                          auto next = cur->next;
                  16
                                                                   unprotect(cur);
                             if (this->head.cas(cur, next)) {
                  17
                              free(cur): break: // unsafe reclamation
                  18
                  19
                                                                   retire(cur);
                           }
                  20
                           return std::move(cur->data);
                  21
                  22
                                                                                                    6
                  23
```

HP's Drawbacks Not Fast & Not Widely Applicable

Not fast: requires per-protect() synchronization with expensive store-load fence



Not widely Applicable: doesn't support "chained retirement"



SMR Algorithm #2 Epoch-Based Reclamation (EBR)

Fast: synchronization for each active state

Widely applicable: Protection for all potential accesses



Epoch Consensus



EBR's Example EBR-Protected Treiber's Stack



EBR's Drawback: Not Robust

If a thread doesn't exit its active state, reclamation is indefinitely blocked.



SMR Algorithms Literature



Pointer-and-Epoch-Based Reclamation



Making EBR Robust with Ejection



PEBR in a Nutshell



SMR Algorithms Literature: Ejection



Pointer-and-Epoch-Based Reclamation



Wide Applicability by Ejection Notification



Safety Requirement:

When ejected, don't start traversal from the previously protected blocks.

Wide Applicability in Practice



Pointer-and-Epoch-Based Reclamation



1. Hybrid of EBR and HP using **ejection**.

- 2. Widely applicable API even in the presence of ejection
- 3. Robust, self-contained and compact ejection algorithm

PEBR is Fast and Robust

Throughput

Peak Memory Usage



What Else Is in the Paper?

